

Mader Tools

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The deep theorem of Mader concerning the number of internally disjoint H -paths is a very powerful tool. Nevertheless its use is very difficult, because one has to deal with a very reach family of separators. This paper shows several ways to strengthen Mader's theorem by certain additional restrictions of the appearing separators.

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1 Preliminaries and Results

For notations not defined here we refer to (1). Unless otherwise stated, k is an arbitrary integer, G is an arbitrary finite simple graph (loops and multiple edges are forbidden), U is an arbitrary subgraph of G , X and H are arbitrary disjoint subsets of $V(G)$ and Y is an arbitrary subset of $E(G - X - H)$. A path having exactly its endvertices in H is called an H -path. The maximum number of independent H -paths we denote by $p_G(H)$. $[Y]$ denotes the graph with edge set Y whose vertex set is the set of all vertices incident with at least one edge of Y . Let $\mathcal{C}(G)$ denote the set of components of G and $\partial_G(U)$ denote the set of vertices of U incident with at least one edge of $G - E(U)$. A pair (X, Y) is called H -separator of G , if each H -path of G contains a vertex of X or an edge of Y . Let \mathcal{S} be the set of all H -separators of $G - E(G[H])$. A vertex x' of G is called *big brother* of a vertex x of G , if the neighborhood of x' in G contains the neighborhood of x in $G - x'$.

According to (1) we define the permeability of a pair (X, Y) by:

$$M_G(X, Y) = |X| + \sum_{C \in \mathcal{C}([Y])} \left\lfloor \frac{|\partial_{G-X}(C)|}{2} \right\rfloor$$

Mader's Theorem (cf. (2)) can be rewritten as follows (cf. (1).)

Theorem 1 (Mader, 1978)

$$p_G(H) = |E(G[H])| + \min\{M_G(X, Y) \mid (X, Y) \in \mathcal{S}\}$$

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Note, that here H is a set of vertices. To get this from the version of Mader's theorem in (1), you have to apply the version of (1) with the graph $G[H]$ instead of H .

Let a subset \mathcal{S}' of \mathcal{S} be a *Mader-Set*, whenever Theorem 1 remains valid if \mathcal{S} is replaced by \mathcal{S}' . In other words, a subset \mathcal{S}' of \mathcal{S} is a Mader-Set, iff for each element (X, Y) of \mathcal{S} there is an element (X', Y') of \mathcal{S}' with $M_G(X', Y') \leq M_G(X, Y)$. Note that a subset of \mathcal{S} containing a Mader-Set is a Mader-Set, too.

The following conditions for elements (X, Y) of \mathcal{S} will be discussed:

- *Odd Border Condition (OB)*

For each component C of $[Y]$ the number $|\partial_{G-X}C|$ is odd.

- *Big Brother Vertex Condition (BV)*: If $x \in X$ and x' is a big brother of x , then $x' \in X$.
- *Symmetric Edge Condition (SE)*: If v and v' are two vertices of $G - H - X$ such that the neighborhood of v' in $G - v$ equals the neighborhood of v in $G - v'$, then the neighborhood of v' in $[Y] - v$ equals the neighborhood of v in $[Y] - v'$.
- *Edge Component Condition (EC)*: For each edge e of $G - H - X - Y$ and each component C of $[Y] \cup (V(G - H - X), \emptyset)$ there is a path P in $G - X - Y - C$ containing an element of H and an endvertex of e .
- *Half Border Condition (HB)*: For each $C \in [Y]$ and each $B \subseteq \partial_{G-X}C$ with $2|B| \geq |\partial_{G-X}C|$ there are two vertexdisjoint *HB*-paths in $G - X$.

For a subset Q of the set of conditions $\{OB, BV, SE, EC\}$ let $\mathcal{S}(Q)$ be the subset of \mathcal{S} satisfying all conditions in Q . Our main results are as follows:

Theorem 2 $\mathcal{S}(\{OB, SE, HB, EC\})$ is a Mader-Set.

Theorem 3 $\mathcal{S}(\{BV, SE, HB, EC\})$ is a Mader-Set.

Theorem 4 There is a graph G and a subset H of $V(G)$ such that $\mathcal{S}(\{OB, BV\})$ is not a Mader-Set.

In other words, Theorem 2 and Theorem 3 state, that for each graph G and each subset H of $V(G)$ the set $\mathcal{S}^*(G, H)$ of H -separators of G with minimal permeability has (possibly equal) elements (X_1, Y_1) and (X_2, Y_2) such that (X_1, Y_1) satisfies the Odd Border Condition, the Symmetric Edge Condition, the Half Border Condition and the Edge Component Condition, and (X_2, Y_2) satisfies the Big Brother Vertex Condition, the Symmetric Edge Condition, the Half Border Condition and the Edge Component Condition.

Theorem 4 states, that there is a graph G and a subset H of $V(G)$, such that none of the elements of $\mathcal{S}^*(G, H)$ satisfies the Odd Border Condition and the Big Brother Vertex Condition.

2 Motivation

Why dealing with such mysterious conditions? The Odd Border Condition helps to simplify the formula for the permeability of an H separator:

Theorem 5 Let G be a graph, H be a subset of G , and (X, Y) be an H -separator of G satisfying the Odd Border Condition. Then for the permeability of (X, Y) the following equation holds:

$$M_G(X, Y) = |X| + \frac{|\partial_{G-X}[Y]| - |\mathcal{C}([Y])|}{2}$$

In order to motivate the remaining three conditions, we regard an application of Mader's Theorem: Suppose, a function f mapping H into the set of nonnegative integers is given. We are interested in a 'separator-like' condition for the existence of a set of p independent H -paths such that in the graph U being the union of all this paths $f(h) \geq d_U(h)$ holds for all $h \in H$. Such a problem appears for instance, if one wants to prove the f -factor theorem with help of Mader's Theorem.

Let the graph $R(G, f)$ be obtained from G by the following procedure: Let G' be the graph obtained from G by intersecting each edge e of $G[H]$ by a vertex h_e . In G' sequentially replace each vertex v of H by a complete bipartite graph R_v whose partition classes A_v and B_v satisfy $|A_v| = d_G(v) + 1$ and $|B_v| = f(v)$. In each step each edge incident with v (say (u, v)) of G' has to be replaced by an edge (u, a) with $a \in A_v$ such that in the resulting graph $R(G, f)$ only one vertex a_v of A_v has all its neighbors in B_v . We call $R(G, f)$ the f -replacement of G .

The set $H_R(G, f) = \{a_v | v \in H\}$ we call f -replacement of H in G . With this definitions we find the following lemma:

Lemma 6 G has a set of p independent H -paths such that each vertex v of H is contained in at most $f(v)$ of this paths if and only if $R(G, f)$ has a set of p independent $H_R(G, f)$ -paths.

Using Mader's Theorem for $R(G, f)$ instead of G and $H_R(G, f)$ instead of H we get

Lemma 7 G has a set of p independent H -paths such that each vertex v of H is contained in at most $f(v)$ of this paths if and only if each $H_R(G, f)$ -separator (X, Y) of $R(G, f)$ satisfies $p < p(X, Y)$.

Now, we are nearly done. We have to retranslate this condition to a condition for the graph G , the set H , and the function f only. To reconstruct G from $R(G, f)$, for each $v \in H$ we have to contract the graph R_v to the vertex v , and after that for each $e \in E(G[H])$ we have to delete h_e and to add e . But, without any knowledge about a special structure of $H_R(G, f)$ -separators in $R(G, f)$, we loose too much information by doing the contractions.

The situation changes rapidly, if we first apply Theorem 3 with $R(G, f)$ instead of G and $H_R(G, f)$ instead of H . Using this we prove the following Lemma:

Lemma 8 G has a set of p independent H -paths such that each vertex v of H is contained in at most $f(v)$ of this paths if and only if each $H_R(G, f)$ -separator (X, Y) of $R(G, f)$ that satisfies the following conditions also satisfies $p < p(X, Y)$.

Here are the conditions:

For each element v of H one of the following statements holds:

1. $V(R_v) \cap X = B_v$ and no edge of Y is incident with A_v ,
2. $V(R_v) \cap X = \emptyset$ and Y contains each edge of $R(G, f)$ incident with $A_v \setminus \{a_v\}$.
3. $V(R_v) \cap X = \emptyset$ and no edge of Y is incident with A_v .

For each edge e of $G[H]$ we have $h_e \in X$ if and only if for each edge v incident with e the third statement ($V(R_v) \cap X = \emptyset$ and no edge of Y is incident with A_v) holds.

By Lemma 8, it is possible to interpret the resulting structure in G , directly. For this, let a pair (X, Y) be (G, H) -valid, if $G - X - Y$ has no H -path and $\partial_{G-X}[Y]$ is disjoint to H .

We derive the following Theorem:

Theorem 9 Given a graph G , a subset H of its vertex set, and a function f that maps H to the set of non-negative integers.

The maximum number of independent H -paths, for which each vertex v of H is contained in at most $f(v)$ of these paths, equals the minimum of

$$|E(G[H \setminus (X \cup V([Y]))])| + |X \setminus H| + \sum_{x \in H \cap X} f(x) + \sum_{C \in \mathcal{C}([Y])} \left[\frac{1}{2} \left(|\partial_{G-X} C| + \sum_{v \in H \cap V(C)} f(v) \right) \right]$$

taken over all (G, H) -valid pairs (X, Y) .

References

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